

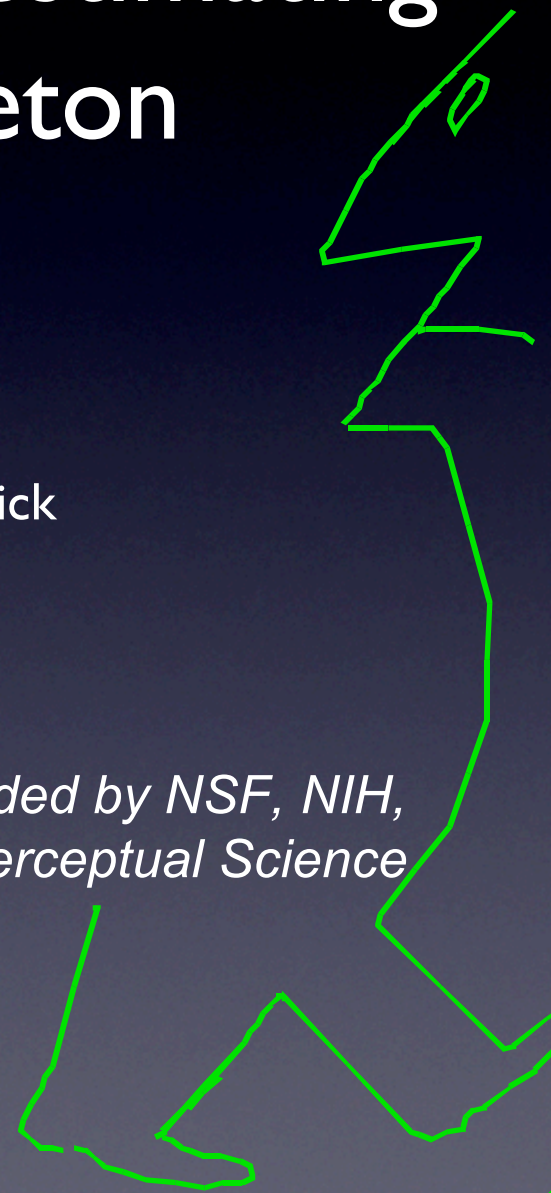
"Explaining" a shape by estimating its generating skeleton

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Joint work with Manish Singh

*Funded by NSF, NIH,
Rutgers IGERT in Perceptual Science*

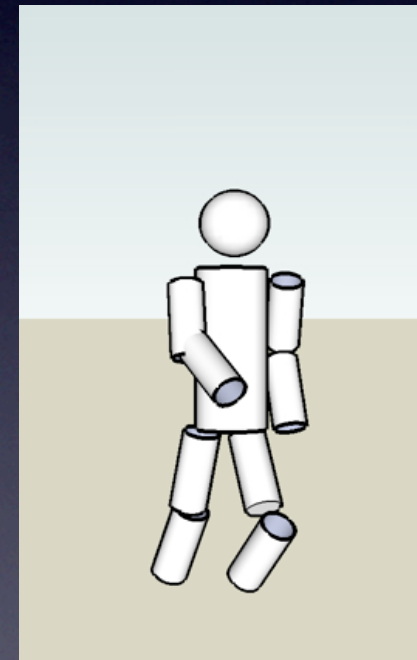


Motivation

- We seek an effective *part-based* representation for shape
- Skeletal and medial axis representations are appealing...



(apologies to Marr & Nishihara, 1978)

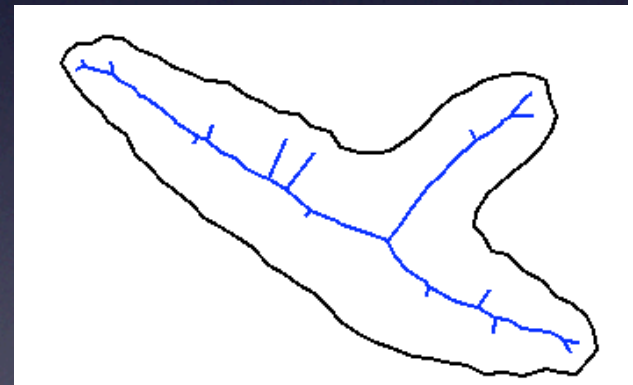
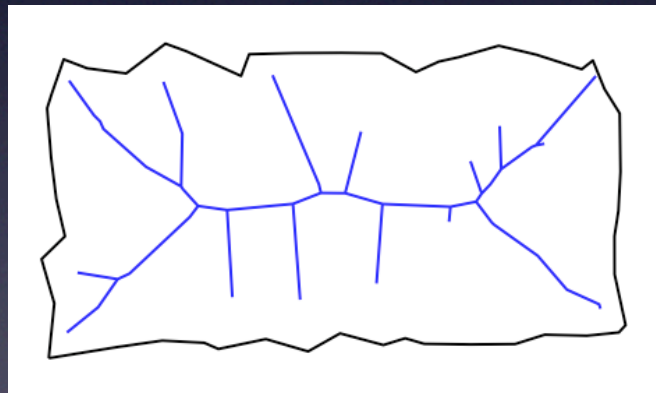
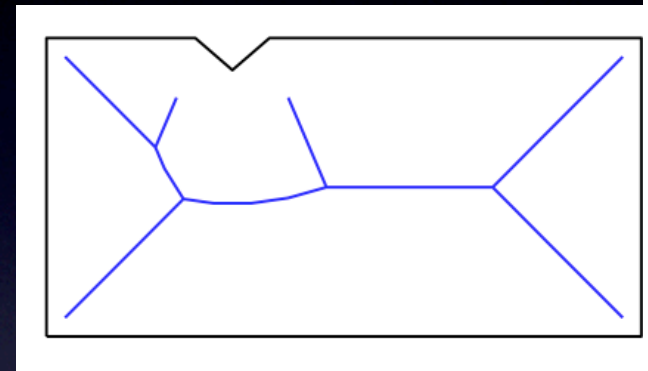
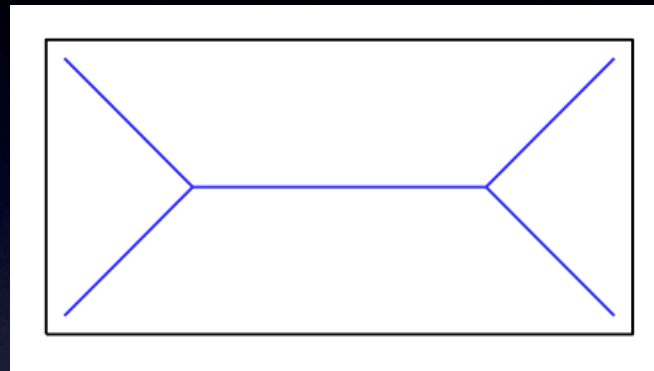


“Geon-guy” (apologies to
Biederman 1987)

...but problematic

Medial axis
computation often
gives
counterintuitive
results (*forking*)

...and is very
sensitive to *noise*
on the contour



These problems ruin what would otherwise be an
isomorphism between *axes* and *parts*

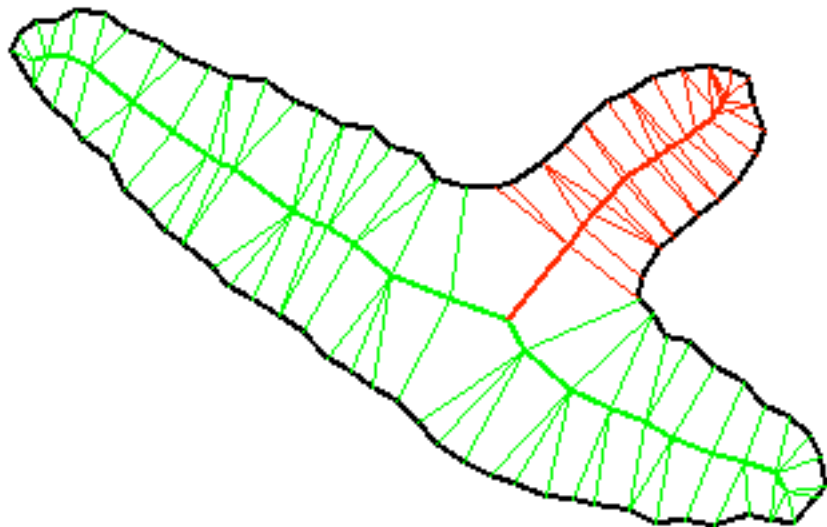
A different approach

- Computing medial axis representations is usually regarded as a “geometry problem”
- We view it as a *probabilistic inference* problem
- The goal is to estimate the shape’s *generative skeleton*—the skeleton from which it “grew”.

Bayesian estimation of the shape skeleton

- Define a **prior** on skeletons $p(\text{skel})$
- Define a **generative model** for shape given a skeleton, which defines the **likelihood** $p(\text{shape}|\text{skel})$
- Then we simply maximize the **posterior**
$$p(\text{skel}|\text{shape}) \propto p(\text{skel})p(\text{shape}|\text{skel})$$
- Equivalent to minimizing the description length
$$-\log p(\text{skel}|\text{shape}) \propto -\log p(\text{skel}) + -\log p(\text{shape}|\text{skel})$$
$$= \text{DL}(\text{skel}) + \text{DL}(\text{shape given skel}) \text{ in MDL-speak}$$

Forward model / generative model / likelihood function



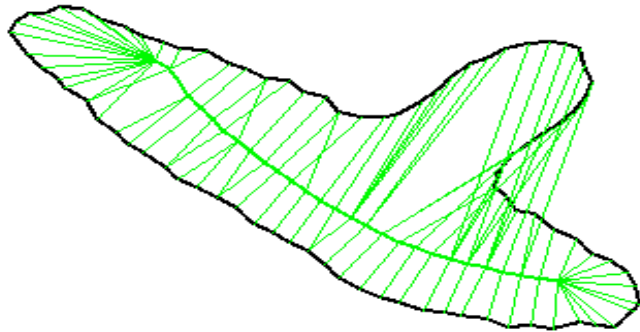
A skeleton...

*...sprouts “ribs” in random direction
(centered on normal)*

...of random lengths

*...whose endpoints join to
become the shape.*

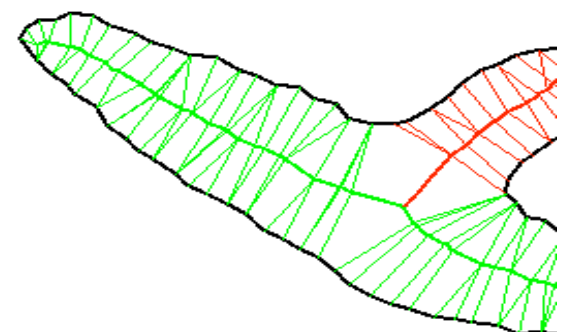
Inverse inference / estimation / posterior



Too simple...



Too complex...



Just right!

- Goal: Over all skeletons, find the one with maximum posterior $p(\text{shape}|\text{skel})p(\text{skel})$, called the maximum a posteriori or **MAP skeleton**
- This skeleton best “explains” the shape.

The prior on skeletons

A hierarchical generalization of our prior on contours $p(C)$:

A skeleton with n axes has prior $p(\text{skel}) =$

$$p_a p(C_1) \cdot p_a p(C_2) \cdot \dots \cdot p_a p(C_n) = p_a^n \prod_i p(C)$$

and complexity $-\log p(\text{skel})$

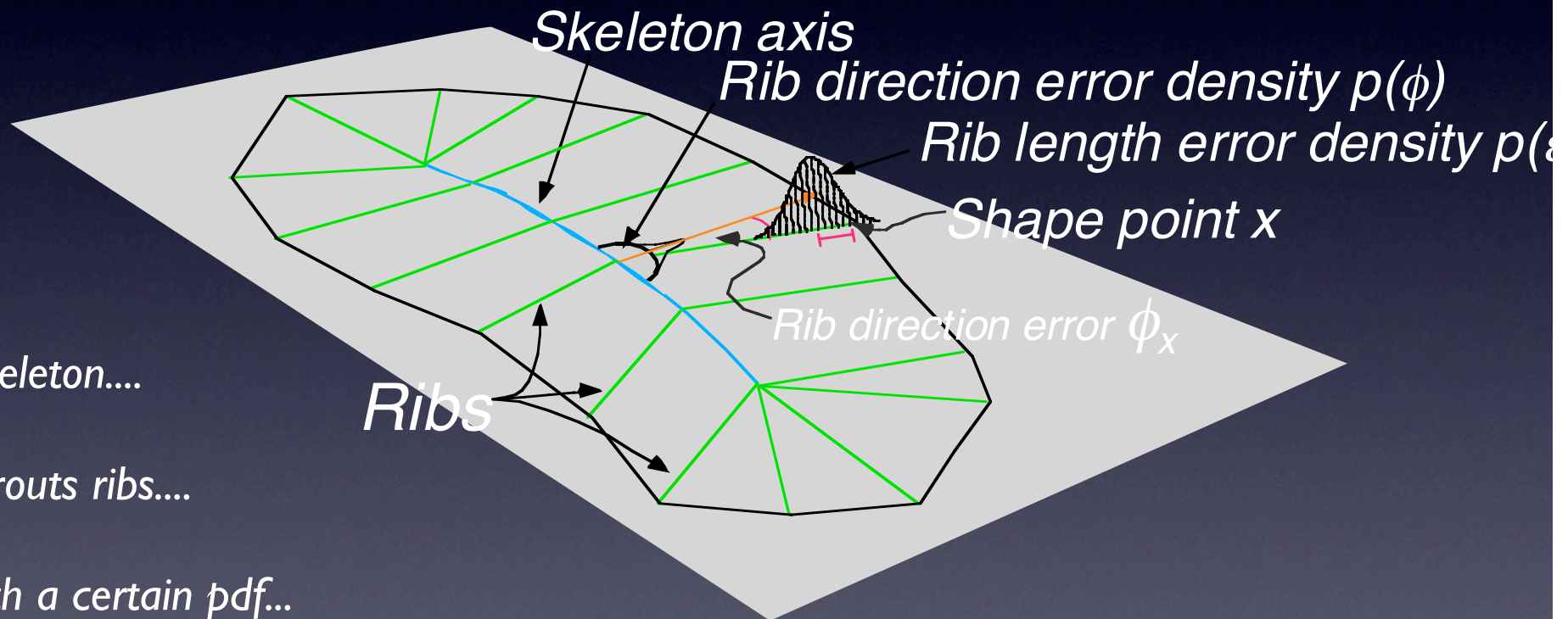
$$n \log p_a + \sum_i \log p(C_i)$$

Branching complexity

Summed axial curve complexity

Increasing skeleton complexity / decreasing prior

Generative (likelihood) model for shapes



Ribs

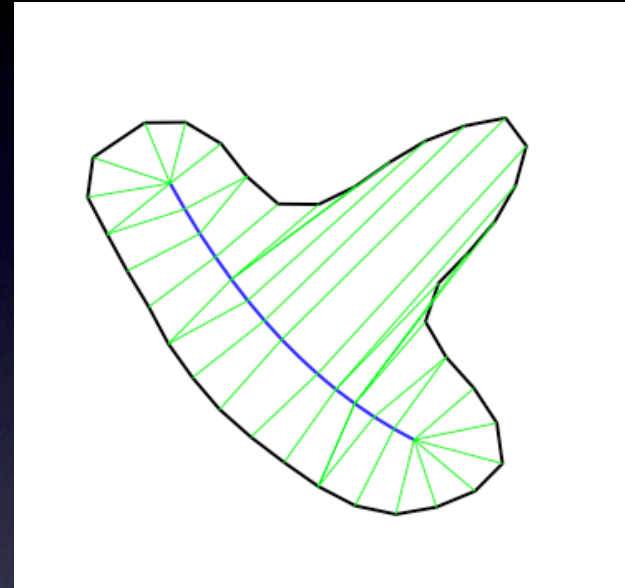
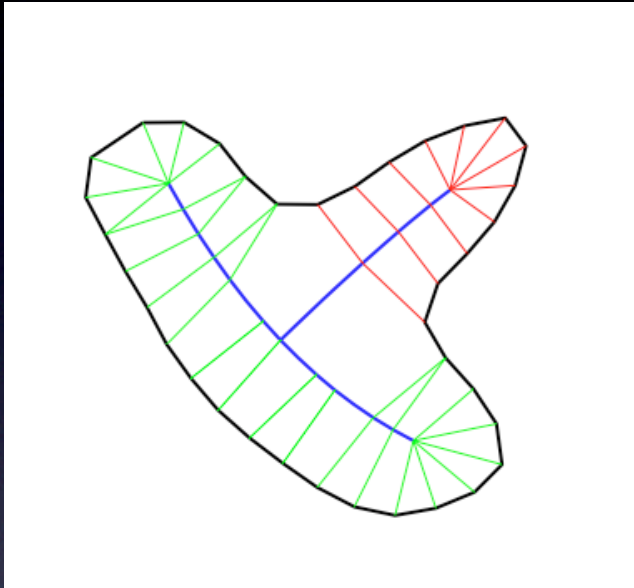
A skeleton....

...sprouts ribs....

...with a certain pdf...

...whose endpoints join to form the shape.

Bayesian (posterior ratio) criterion for the “significance” of an axis



Compare
posteriors

with the axis

vs.

without the axis

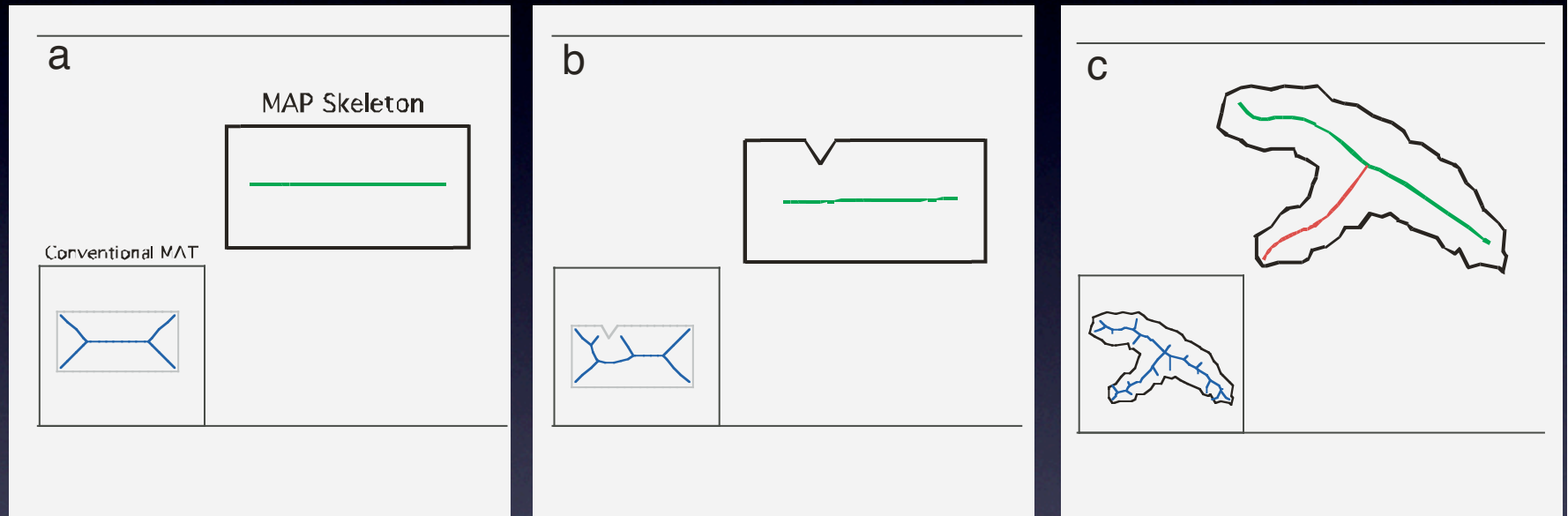
$$\text{If } \frac{p(\text{skel} + \text{axis} | \text{shape})}{p(\text{skel} | \text{shape})} > 1, \text{ keep the axis.}$$

Estimating the skeleton

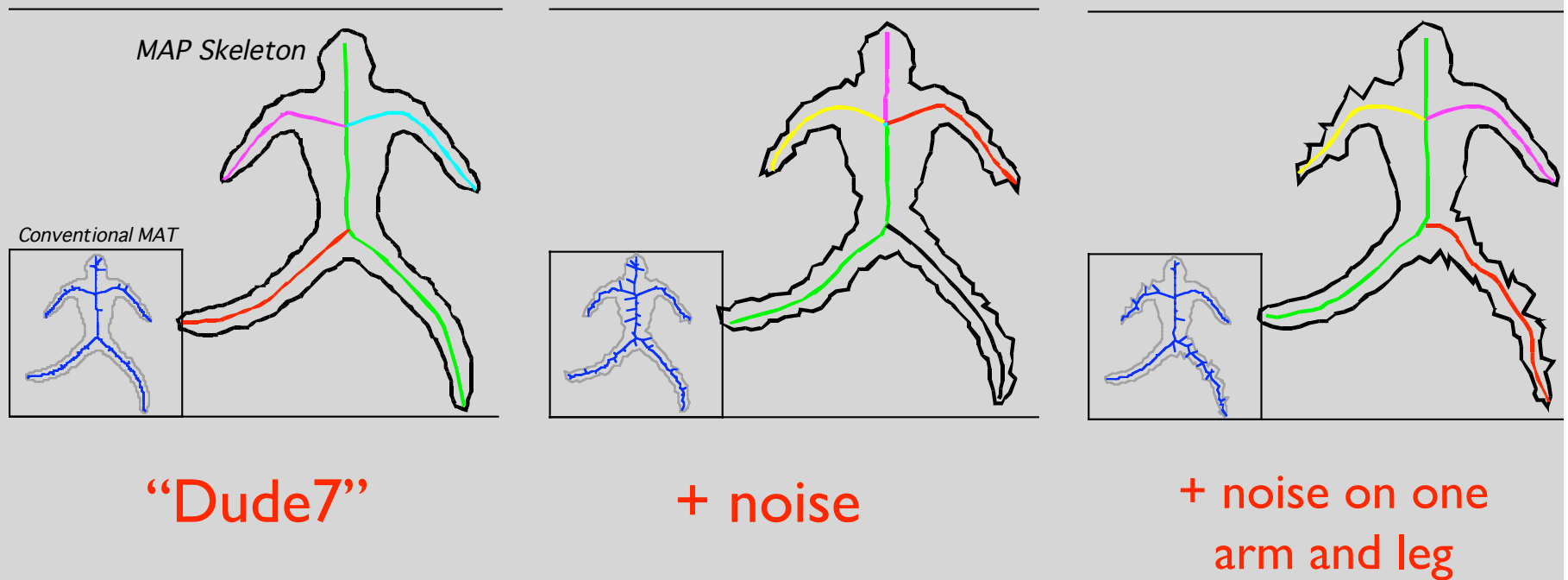
the fine print

- Initialize skeleton
(we use a conventional Voronoi-based medial axis)
- Prune “nonsignificant” axes using posterior ratio rule
- Parameterize skeleton estimate
(we use a piecewise cubic spline approximation)
- Begin gradient descent in skeleton parameter space
(we use a home-brewed variant of Expectation-Maximization)
- Many other details I’m not mentioning

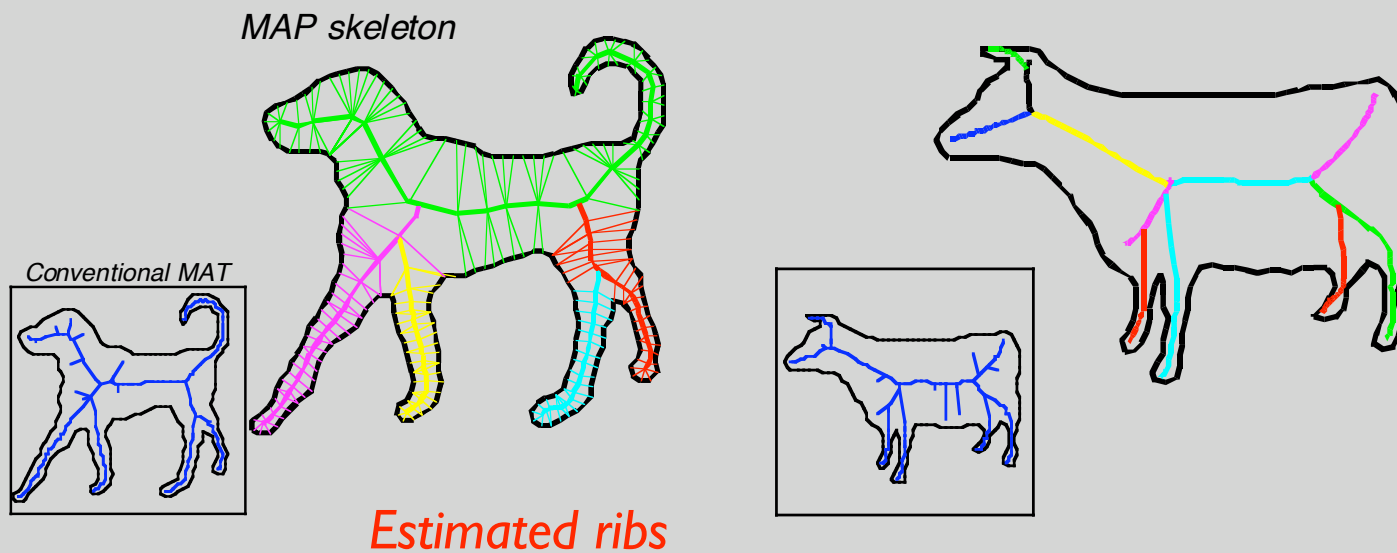
Results



Robustness against contour noise



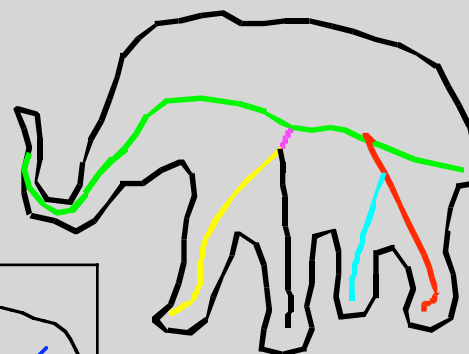
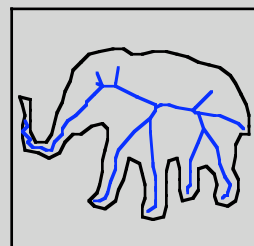
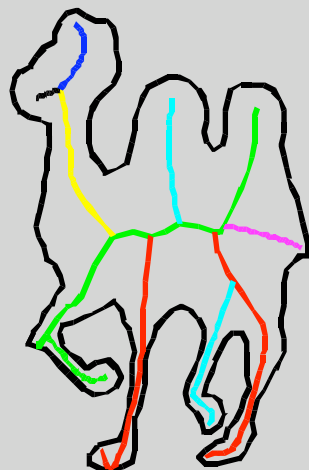
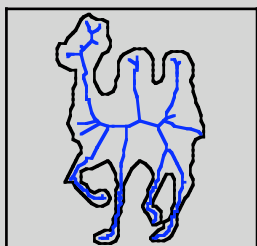
Dog, cow



Camel, elephant

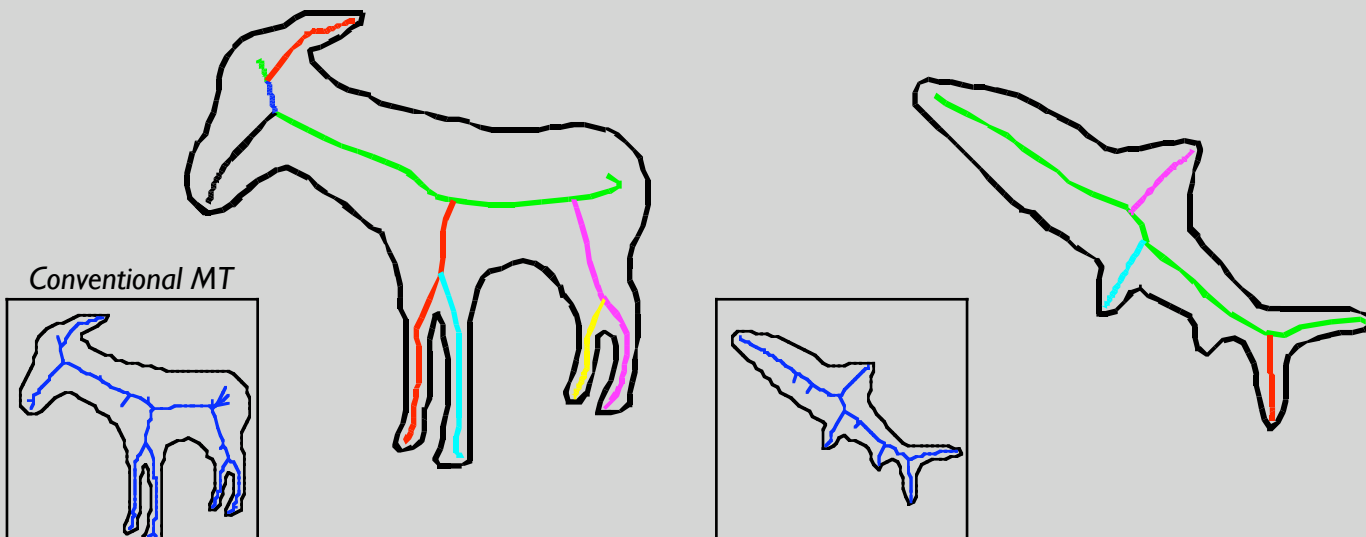
MAP skeleton

Conventional MT



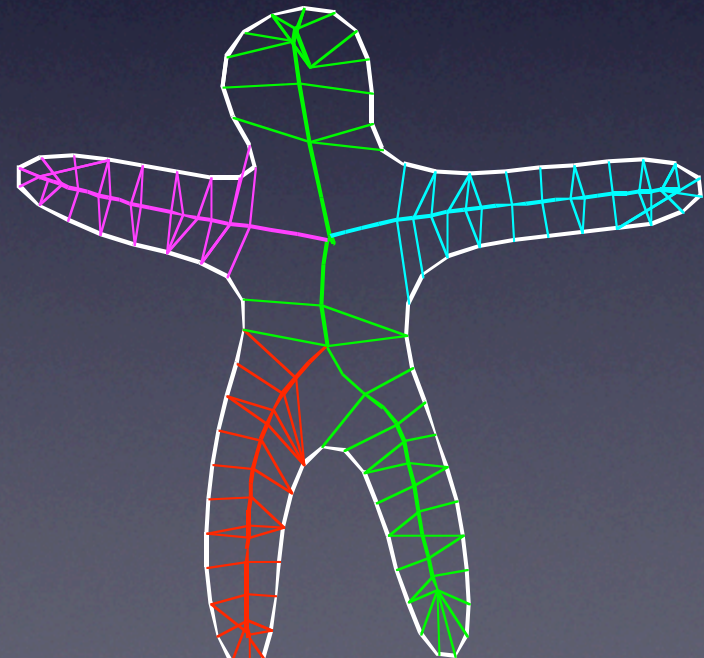
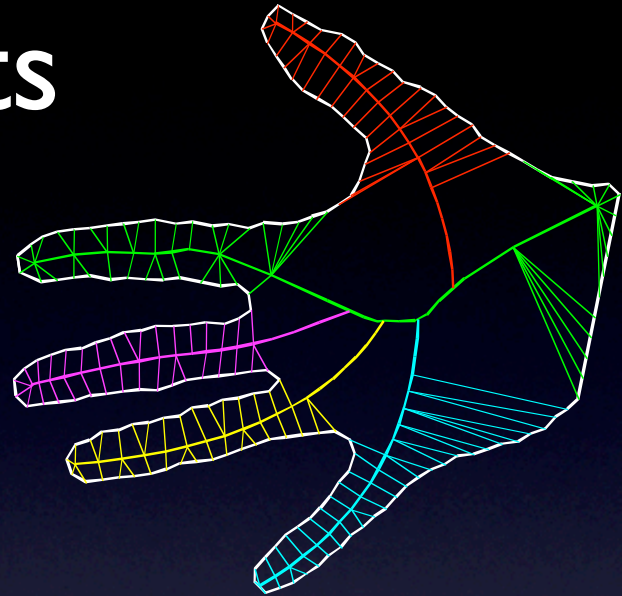
Donkey, fish

MAP skeleton



Skeletons and parts

- Distinct axes in the estimated skeleton “own” (explain) points on the contour
- Many known principles of part decomposition approximately “fall out” of MAP skeleton estimation
 - minima rule (Hoffman & Richards, 1984)
 - short cuts (Singh, Seyranian, & Hoffman, 1999)
 - maximization of convexity (Rosin, 2000)
- Unifies theory of part-boundaries with theory of part-cuts

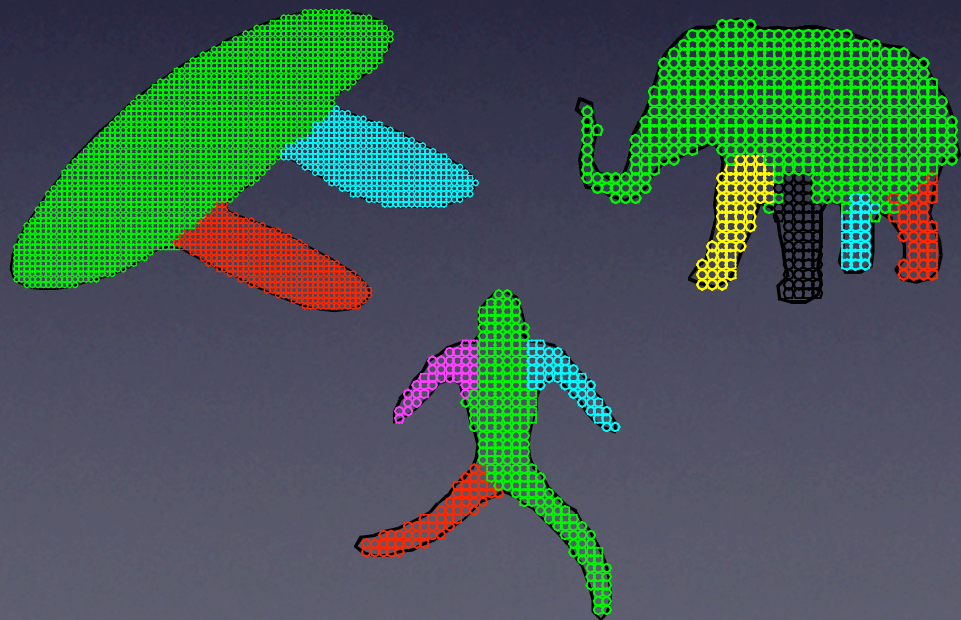
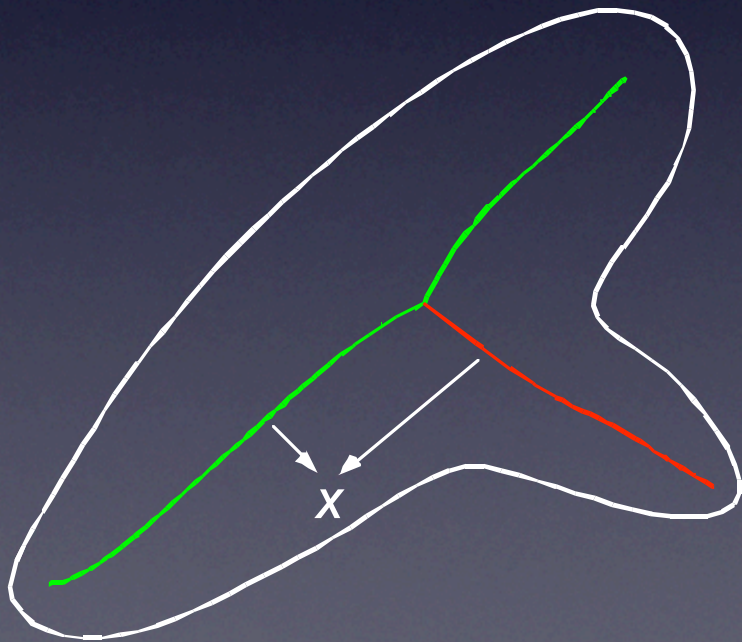


Extending “ownership” to interior regions

- For each interior point x , determine axial ownership by

$$p(x \text{ owned by } A_i) = p(A_i)p(x|A_i)$$

$$\propto \frac{1}{1 + \text{depth}(A_i)} f(d(x, A_i))$$



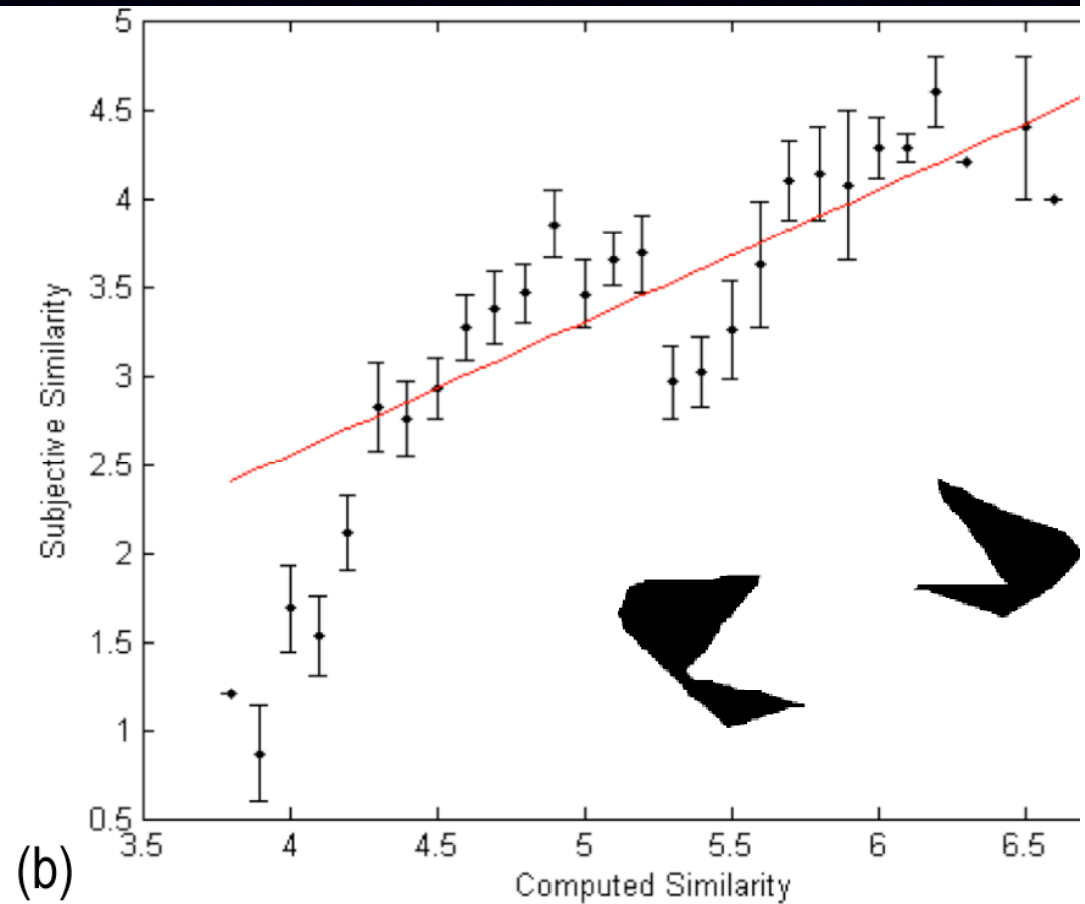
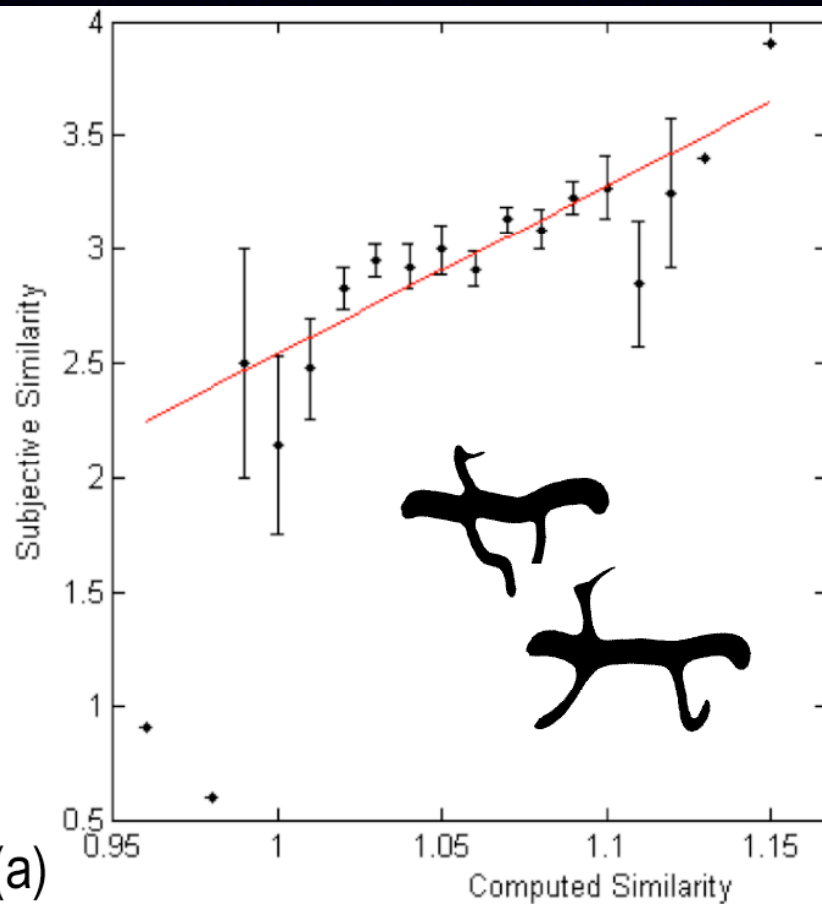


with Erica Briscoe

Shape similarity

- Given shapes x and y , what is $\text{sim}(x,y)$?
- Conceptualization: shapes are similar to the degree that they seem to *share common generative origins*
- Operationalization: similarity is given by the “cross-likelihoods”
$$\text{sim}(x,y) \sim [p(\text{shape}_x|\text{skel}_y) + p(\text{shape}_y|\text{skel}_x)]/2$$
- Experiments: Similarity ratings on all pairs of 25 shapes, various types: “metric” differences, part-structure differences, non-axial shapes...

Similarity results



3D shape from the skeleton

- The generative model can be easily extended to 3D
- “Inflate” the shape to produce a complete 3D model from the 2D skeleton

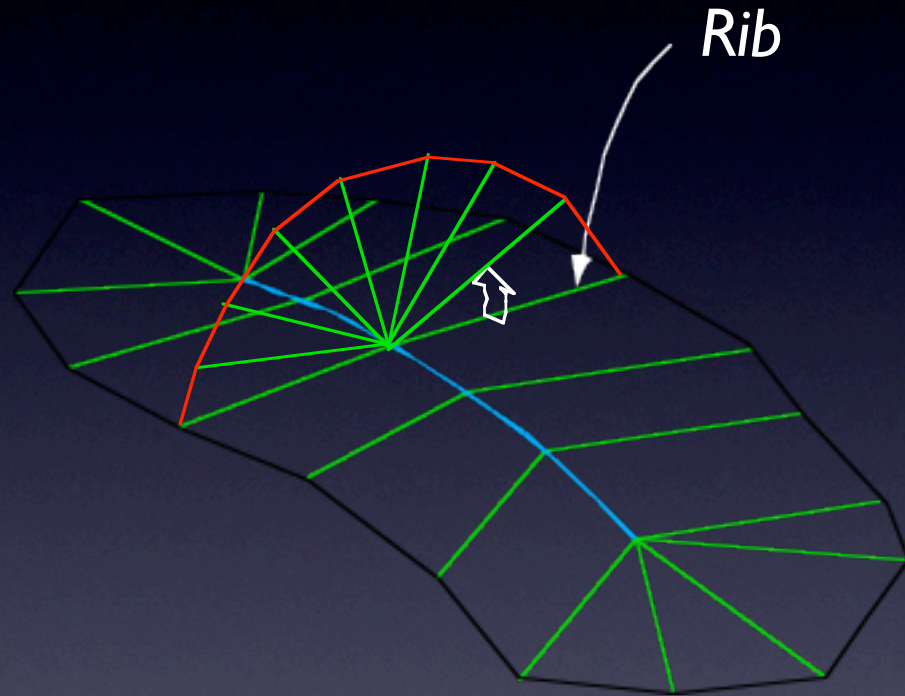
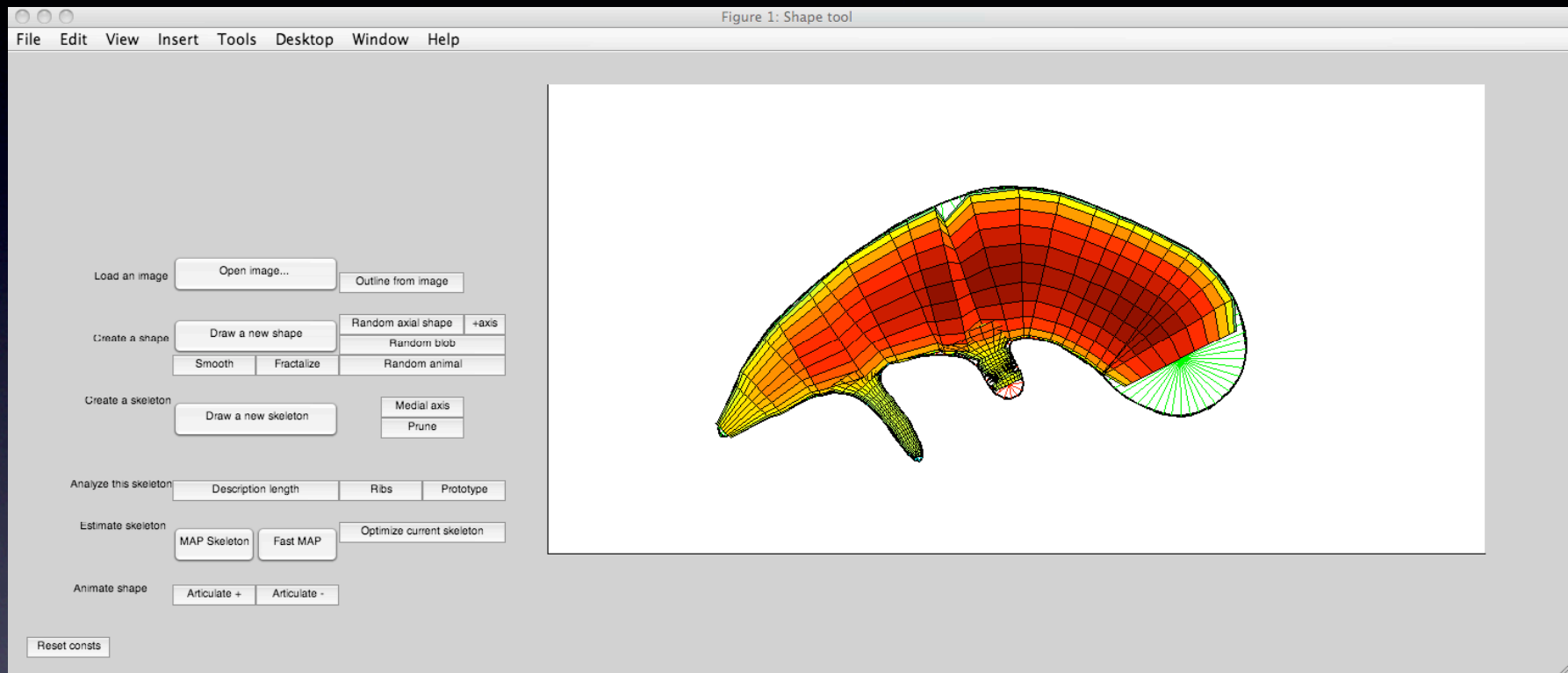


Figure 1: Shape tool



Statistics of natural shapes

- “Naturalizing the prior”

In place of the naïve complexity prior, draw prior densities from *statistics of natural shapes*

- The goal is to find “meaningful” shape parameters and tune the representation to the environment



Sample domains: animals and leaves

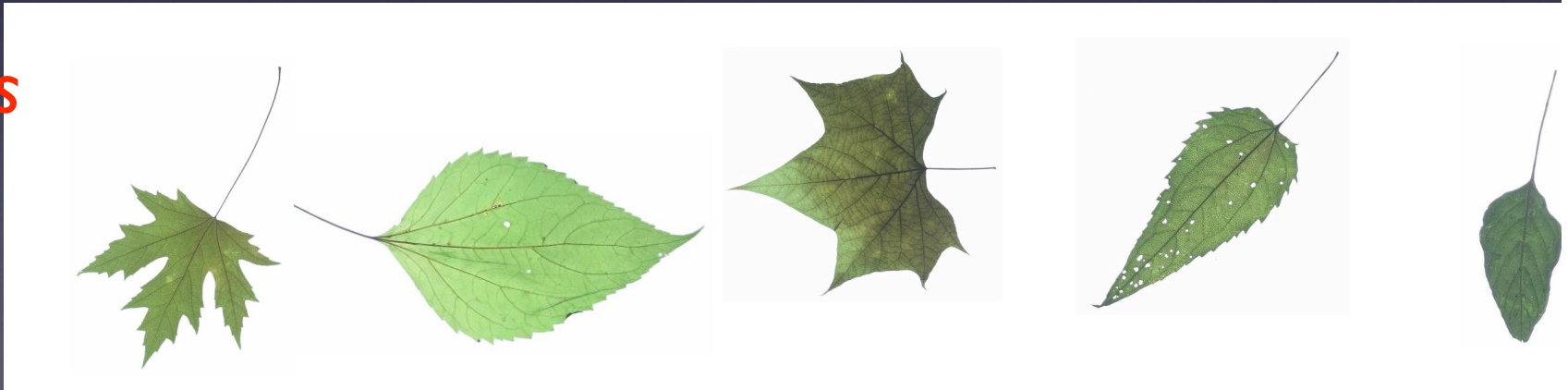
with John Wilder

We gathered skeleton statistics from two shape databases...

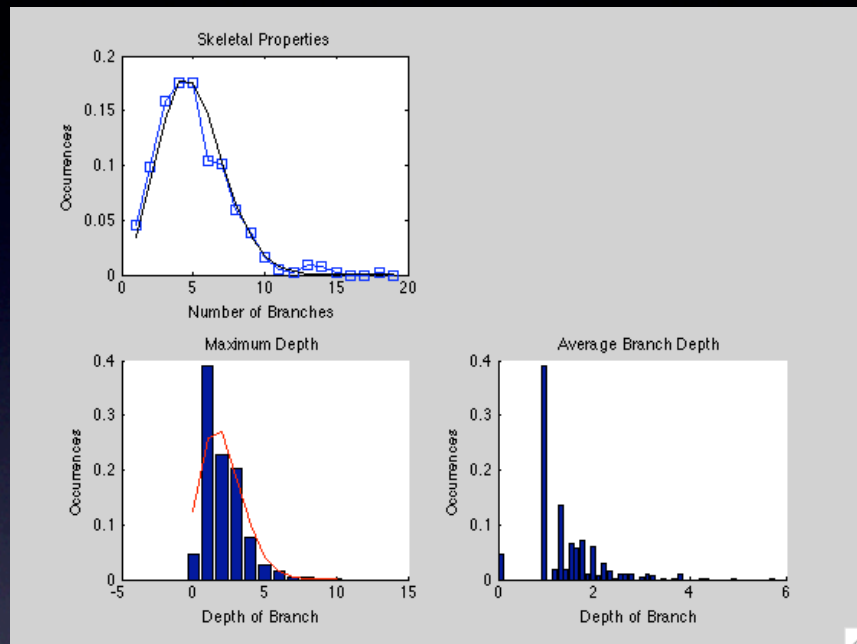
Animals



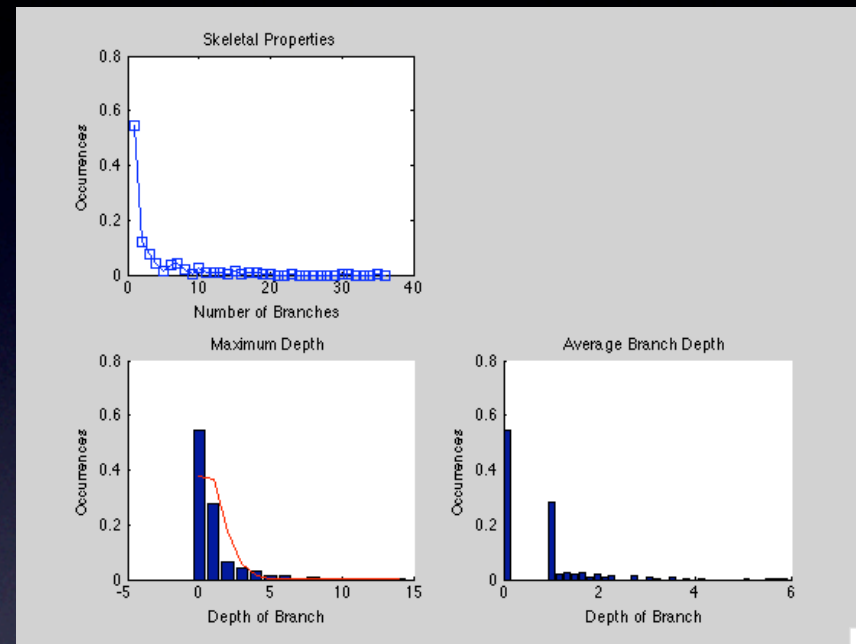
Leaves



Empirical distributions of skeleton parameters



Animals



Leaves

Objectively quantifying “natural kinds”

Summary and conclusions

- Shape is poorly understood, even in the 2D case

- skeletons are important

- The **generating skeleton** as a unifying conceptualization of shape

- Principled theoretical framework based on the idea of “explaining” the shape*

- Bayesian estimation of the MAP skeleton yields part decomposition, similarity measurement, structure, etc.*

- Many other extensions just beginning to be pursued

The end